

# Introduction to mediation analysis

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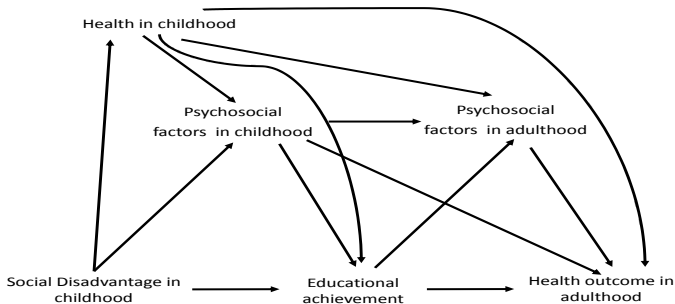


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- In other words we are interested in the study of **mediation**.

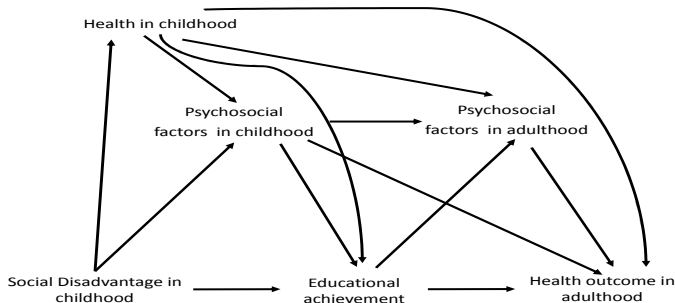
# Example: mediation in life course epidemiology

Focus on **distal** exposures for **later** life outcomes:



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Interest: disentangle the underlying **processes**.

- What proportion of the effect of prenatal care on infant mortality is mediated by medically-induced pre-term birth?

# Other examples

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- What proportion of the effect of prenatal care on infant mortality is mediated by medically-induced pre-term birth?
- Is cognitive behavioral therapy acting via increased compliance in reducing suicide rates?
- Is the effect of tamoxifen on CVD mediated/modified by other drugs taken to control its symptoms?



# The study of mediation

- Two main strands in the literature for the study of mediation:
  - **Social sciences / psychometrics** (Baron and Kenny, 1986)
  - **Causal inference literature** (Robins and Greenland, 1992; Pearl, 2001)
- The first more accessible, but also misused/misunderstood
- The second more rigorous and general, but more complex

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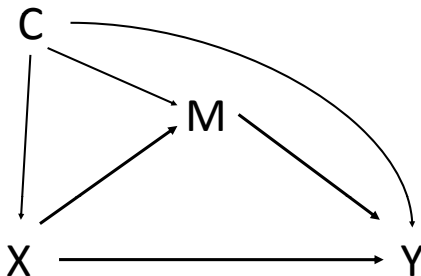
## Aims:

- outline these two approaches
- compare them and show important differences
- show an application

- 1 SEM framework
- 2 Causal inference framework
- 3 Comparison
- 4 A life course epidemiology example
- 5 Summary

# Simplify the question: one mediator

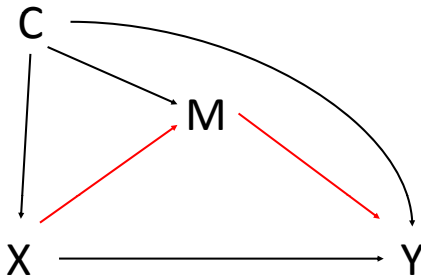
Exposure  $X$ , mediator  $M$ , outcome  $Y$  and confounders  $C$ .



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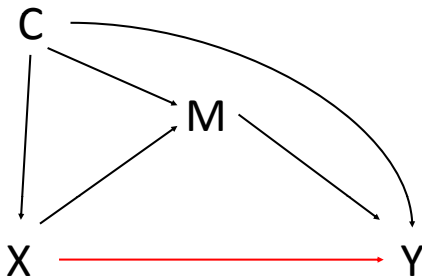
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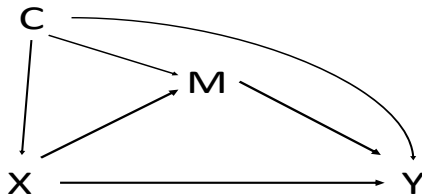


Exposure  $X$ , mediator  $M$ , outcome  $Y$  and confounders  $C$ .  
Mediation leads to separate the two pathways: indirect and **direct**.



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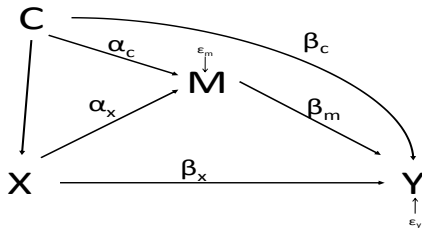
## A Simple linear Structural Equation Model (LSEM) (1)



Consider the LSEM corresponding to this diagram:



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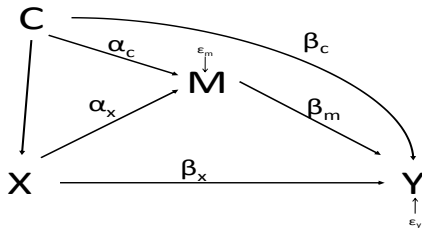


Consider the LSEM corresponding to this diagram:

$$\begin{cases} M &= \alpha_0 + \alpha_x X + \alpha_c C + \epsilon_m \\ Y &= \beta_0 + \beta_x X + \beta_m M + \beta_c C + \epsilon_y \end{cases} \quad (1)$$

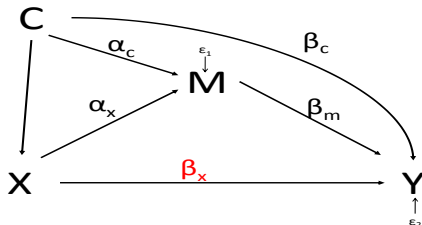
$\epsilon_m$  and  $\epsilon_y$  uncorrelated error terms, also uncorrelated with the explanatory variables in their equations.

## A Simple linear Structural Equation Model (LSEM) (2)



If the model is correctly specified:

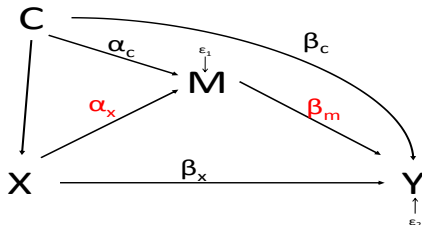
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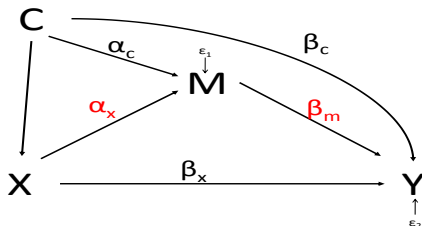
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If the model is correctly specified:

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- the marginal effect of X is  $(\beta_x + \alpha_x\beta_m) \Rightarrow$  **indirect effect** is  $\alpha_x\beta_m$

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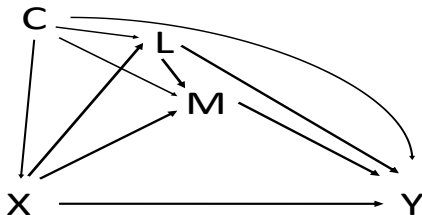


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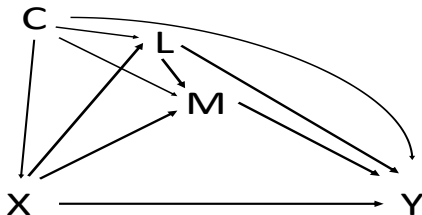
Estimation via ML/OLS; delta method/ bootstrapping to obtain SEs for the indirect effect.

## Intermediate confounders (1)



Here  $L$  is an **intermediate confounder** (endogenous variable) because it is influenced by  $X$ . If  $L$  is a continuous variable:

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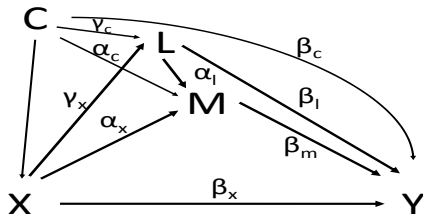


Here  $L$  is an **intermediate confounder** (endogenous variable) because it is influenced by  $X$ . If  $L$  is a continuous variable:

$$\begin{cases} L &= \gamma_0 + \gamma_x X + \gamma_c C + \epsilon_l \\ M &= \alpha_0 + \alpha_x X + \alpha_l L + \alpha_c C + \epsilon_m \\ Y &= \beta_0 + \beta_x X + \beta_m M + \beta_l L + \beta_c C + \epsilon_y \end{cases} \quad (2)$$

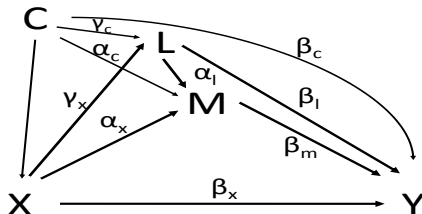
$\epsilon_l$ ,  $\epsilon_m$ , and  $\epsilon_y$  uncorrelated error terms, also uncorrelated with the explanatory variables in their equation.

## Intermediate confounders (2)





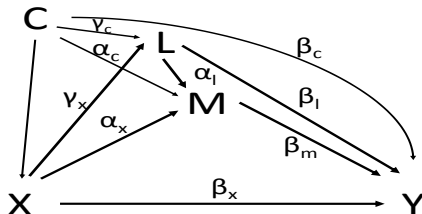
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Following the same steps as before we find, if the model is correctly specified:

- Marginal effect of  $X$  on  $Y$  is  $(\beta_x + \alpha_x\beta_m + \gamma_x\alpha_l\beta_m + \gamma_x\beta_l)$

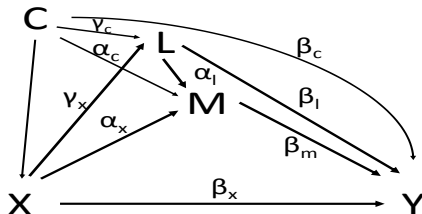
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- Effect mediated via M, the **indirect effect** is  $(\alpha_x\beta_m + \gamma_x\alpha_l\beta_m)$
- Effect not mediated by M, the **direct effect**:  $(\beta_x + \gamma_x\beta_l)$

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- Derivations of direct and indirect effects are always **specific** to a particular model
- For non-linear settings: approximate solutions (and for defining indirect effects only) (Hayes and Preacher, 2010)

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- Explicitly aiming for causal statements, this approach invokes the notion of *“how the world would have been had something been different”*
- Hence use of quantities that are not all observable: *potential outcomes* and the *potential mediators*.

# Potential outcomes

- $Y(x)$ : the potential values of  $Y$  that would have occurred had  $X$  been set, possibly counter to fact, to the value  $x$ .
- $M(x)$ : the potential values of  $M$  that would have occurred had  $X$  been set, possibly counter to fact, to the value  $x$ .
- $Y(x, m)$ : the potential values of  $Y$  that would have occurred had  $X$  been set, possibly counter to fact, to the value  $x$  and  $M$  to  $m$ .

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- For simplicity consider the case where  $X$  is binary
- It also helps to start with the definition of *total causal effect*

# Total Causal Effect (TCE): definition

The average **total causal effect** of  $X$ , comparing exposure level  $X = 1$  to  $X = 0$ , can be defined as the linear contrast <sup>1</sup>:

$$TCE = E[Y(1)] - E[Y(0)]$$

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In general:  $TCE \neq E[Y|X = 1] - E[Y|X = 0]$

hence  $TCE$  cannot be naively estimated from the data.

# Total Causal Effect (TCE): identification

To identify *TCE* we need to infer  $E[Y(1)]$  and  $E[Y(0)]$  from the data.

This is possible under certain assumptions. Those most invoked are:

- (i) **no interference**:  $Y_i$  is not influenced by  $X_j$ ,  $i \neq j$



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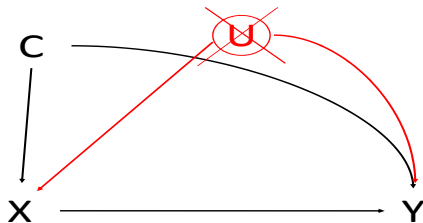
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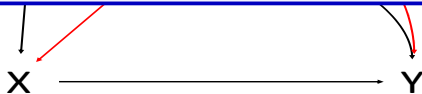
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If these are satisfied, we can infer the *TCE* from the data

$$\sum_c \{E(Y|X = 1, C = c) - E(Y|X = 0, C = c)\} Pr(C = c)$$



# Controlled Direct Effect (CDE): definition

The average **controlled direct effect** of  $X$  on  $Y$ , when  $M$  is controlled at  $m$ , is:

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- By keeping  $M$  fixed at  $m$ , we are getting at the direct effect of  $X$ , unmediated by  $M$ .

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- **In general**  $CDE(m)$  varies with  $m$

Identification possible under extensions of the earlier assumptions:

- (i) **no interference**
- (ii) **consistency**: extended to include  
 $Y = Y(x, m)$  if  $X = x$  and  $M = m$

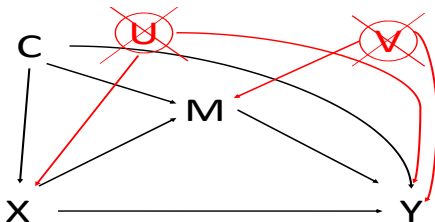


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If these assumptions are satisfied we can infer the **CDE(m)** from the observed data

$$\sum_c \{E(Y|X = 1, M = m, C = c) - E(Y|X = 0, M = m, C = c)\} Pr(C = c)$$

# Pure Natural Direct Effect (PNDE): definition

The average **Pure Natural Direct Effect** of  $X$  on  $Y$  is:

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This is a comparison of two hypothetical worlds:

- In the first,  $X$  is set to 1, and in the second  $X$  is set to 0.
- In both worlds,  $M$  is set to the **natural** value  $M(0)$ , *i.e.* the value it would take if  $X$  were set to 0.
- Since  $M$  is the same (*within* individual) in both worlds, we are still getting at the direct effect of  $X$ , unmediated by  $M$ .

Identification possible, as before, under extensions of the earlier assumptions:

(i) **no interference**

(ii) **consistency**, extended to include:

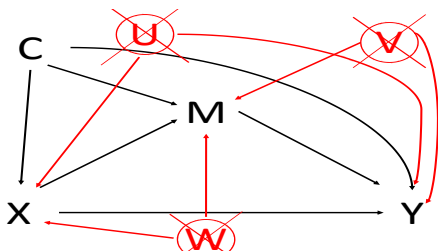
$Y = Y(x, m)$  if  $X = x$  and  $M = m$ ,  $M = M(x)$  if  $X = x$ , and  
 $Y = Y\{x, M(x^*)\}$  if  $X = x$  and  $M = M(x^*)$ .

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# Pure Natural Direct Effect: identification

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- (iv) either **no intermediate confounders** or some restrictions on  **$X - M$  interactions** in their effect on  $Y$

If these assumptions are satisfied: we can infer the *NDE* from the observed data

# Total Natural Indirect Effect (TNIE): definition

The average **Total Natural Indirect Effect** of  $X$  on  $Y$  is:

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This is a comparison of two hypothetical worlds: In both  $X$  is set to 1, while  $M$  is set to the **natural** value when  $X$  is set to 1 or 0.

The same assumptions as for  $PNDE$  are required to identify the  $TNIE$ .

# The identification equations

- Each of these estimands can be identified under certain assumption and via an identification equation, *e.g.*

$$CDE(m) = \sum_c \{E(Y|X = 1, M = m, C = c) - E(Y|X = 0, M = m, C = c)\} Pr(C = c)$$

$$PNDE = \sum_c \left\{ \sum_m \{E(Y|X = 1, M = m, C = c) - E(Y|X = 0, M = m, C = c)\} \right. \\ \left. Pr(M = m|X = 0, C = c) \right\} Pr(C = c)$$

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- These equations can be extended to deal with continuous  $M$  and  $C$  and to include intermediate confounders  $L$ .

# The identification equations

- Each of these estimands can be identified under certain assumption and via an identification equation, *e.g.*

$$CDE(m) = \sum_c \{E(Y|X = 1, M = m, C = c) - E(Y|X = 0, M = m, C = c)\} Pr(C = c)$$

$$PNDE = \sum_c \left\{ \sum_m \{E(Y|X = 1, M = m, C = c) - E(Y|X = 0, M = m, C = c)\} Pr(M = m|X = 0, C = c) \right\} Pr(C = c)$$

- These equations can be extended to deal with continuous  $M$  and  $C$  and to include intermediate confounders  $L$ .
- Their essence is the specification of **conditional expectations** of  $Y$ , **conditional distributions** for  $M$  (and  $L$ ) (and marginal distributions for  $C$ ).



Wide range of options, for most combinations of  $M$  and  $Y$ :

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  - requires correct specification of all relevant conditional expectations and distributions
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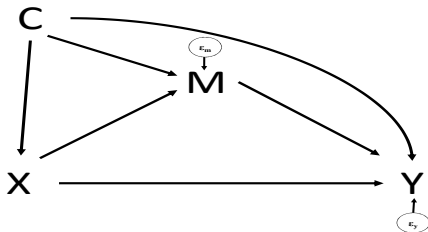
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- **G-computation**—very flexible and efficient but heavy on parametric modelling assumptions:
  - It is the direct implementation of the identification equations
  - requires correct specification of all relevant conditional expectations and distributions
  - implemented in `gformula` command in Stata
- Semi-parametric methods make fewer parametric assumptions:
  - **Inverse probability of treatment weighting (IPTW)**:
    - not practical when  $M$  is continuous
  - Various flavours of **G-estimation**
    - generally more complex to understand

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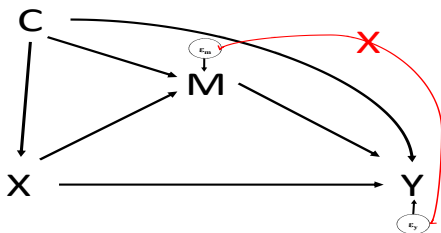
# Revisiting SEMs

## Structural assumptions with no intermediate confounders



# Revisiting SEMs

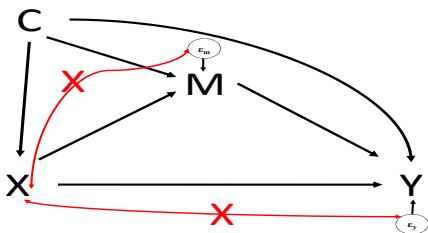
## Structural assumptions with no intermediate confounders



- Disturbances are mutually uncorrelated

# Revisiting SEMs

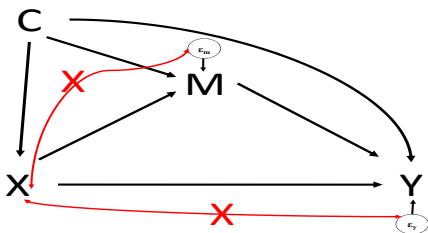
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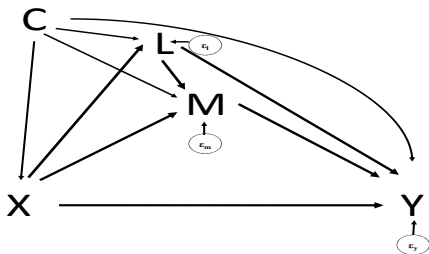
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'Same' as **no unaccounted common causes** for  $M - Y$ ,  $X - Y$ ,  $X - M$ .



# Revisiting the SEM assumptions (2)

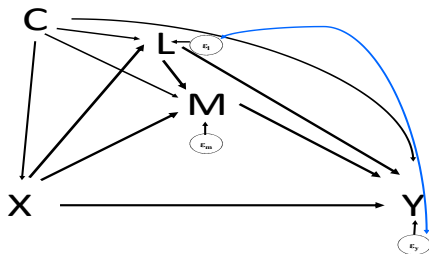
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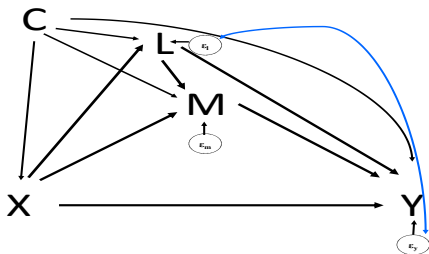
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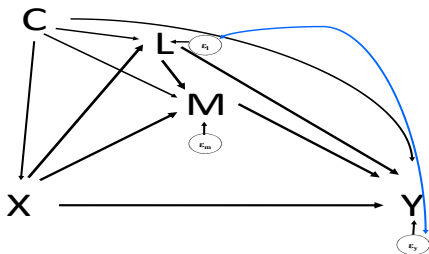
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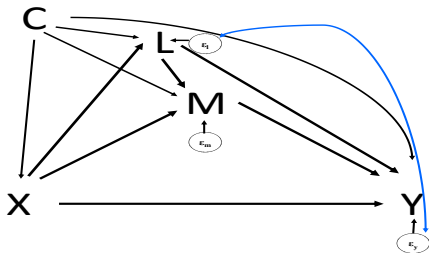
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With linear models, structural assumptions for mediation analysis from the two schools are essentially equivalent

# Revisiting the SEM assumptions (3)

## Parametric assumptions

If a structural model is linear and does not include interactions or other non-linear terms:

- identifying equation for modern causal inference would lead to same estimands as adopting an SEM approach:
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Estimation-by-combination



# Estimation-by-combination

Consider a more general linear SEM:

$$\begin{cases} L &= \gamma_0 + \gamma_x X + \gamma_c C + \epsilon_l \\ M &= \alpha_0 + \alpha_x X + \alpha_l L + \alpha_c C + \epsilon_m \\ Y &= \beta_0 + \beta_x X + \beta_l L + \beta_m M + \beta_{mm} M^2 + \beta_c C + \beta_{xm} XM + \epsilon_y \end{cases}$$

Applying the appropriate identification equations leads to:

$$\begin{aligned} \text{CDE}(m) &= \beta_x + \beta_l \gamma_x + \beta_{xm} m \\ \text{PNDE} &= \beta_x + \beta_l \gamma_x + \beta_{xm} [\alpha_0 + \alpha_l (\gamma_0 + \gamma_c \bar{C}) + \alpha_c \bar{C}] \\ \text{TNIE} &= (\beta_m + \beta_{xm}) (\alpha_x + \gamma_x \alpha_l) + \\ &\quad \beta_{mm} [(\alpha_x + \gamma_x \alpha_l)^2 + 2(\alpha_x + \gamma_x \alpha_l) (\alpha_0 + \alpha_l (\gamma_0 + \gamma_c \bar{C}) \\ &\quad + \alpha_c \bar{C})] \end{aligned}$$

where each of these parameters can be estimated by the model above, leading to the same results as from g-computation.

# Comparison of G-computation and estimation-by-combination

Scenario	Method	PNDE		Estimand TNIE		CDE(0)	
		estimate	(s.e.)	estimate	(s.e.)	estimate	(s.e.)
$Y, M$ , with $C, MX$	true	0.730	-	0.240	-	0.400	-
	g-estimation	0.731	(0.003)	0.238	(0.003)	0.405	(0.003)
	combination	0.731	(0.002)	0.239	(0.001)	0.405	(0.003)
$Y, M$ , with $MX$ and $M^2$	true	0.730	-	0.344	-	0.400	-
	g-estimation	0.730	(0.004)	0.341	(0.004)	0.406	(0.003)
	combination	0.731	(0.002)	0.342	(0.002)	0.406	(0.003)
$Y, M, L$ , with $MX, M^2$	true	0.806	-	0.787	-	0.520	-
	g-estimation	0.806	(0.007)	0.783	(0.008)	0.527	(0.004)
	combination	0.807	(0.002)	0.783	(0.003)	0.527	(0.004)
$Y, M, L$ , with $C, U$	true	0.520	-	0.156	-	0.520	-
	g-estimation	0.521	(0.003)	0.158	(0.003)	0.521	(0.004)
	combination	0.520	(0.002)	0.157	(0.001)	0.520	(0.002)

Datasets of size=1,000,000 generated according to specified model with  $N(0, 1)$  errors and binary  $C$  ( $p = 0.5$ ).

Standard errors obtained via bootstrap for g-computation and the delta method for estimation-by-combination.

# Comparison: summary

With continuous endogenous variables represented by a recursive linear system:

- **structural assumptions** for mediation made by the two approaches **closely related**, even in the presence of intermediate confounders
- fully **parametric estimation** via g-computation is achievable within an **SEM framework**, even in the presence of interactions and other non-linearities, and even if there is unmeasured  $L - Y$  confounding.

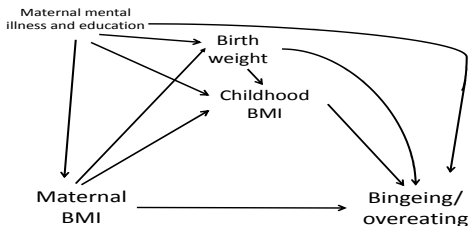
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# Eating disorders (ED) in adolescence

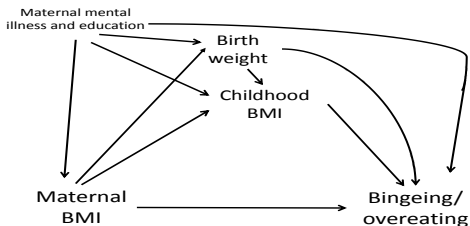
Work in progress: girls in ALSPAC, birth cohort 1991-2

- ED comprise a variety of **heterogeneous diseases**
- Maternal factors possibly important
- **Childhood BMI** a possible mediator
- Data:
  - **Outcome:** ED scores derived from parental questionnaire on the child's psychological distress when aged 13.5y: today focus on "*Binge eating*"
  - **Exposure:** pre-pregnancy maternal BMI (binary,  $> 25\text{kg/m}^2$ )
  - **Mediator:** Childhood BMI (around age 7, age-standardized)
  - **Confounders:** pre-pregnancy maternal mental illness, maternal education, girl's birth weight

# Maternal BMI, childhood BMI and eating disorders



# Maternal BMI, childhood BMI and eating disorders



## The causal question

How much of the effect of maternal BMI on her daughter's ED score is due to its effect on the child's BMI?

# More specifically ...

We can ask either of these question:

What effect does intervening on maternal BMI have on later ED if we could also intervene on each child BMI and set it to a particular level?

- **Controlled Direct Effect**

What effect does intervening on maternal BMI has on later ED in a world where the effect of maternal BMI has no effect on her child BMI?

- **Natural Direct Effect**



Identification requires assumptions that allows us to use observed data to derive potential outcomes. According to the estimand, varying specifications of:

- (i) **no interference**
- (ii) **consistency**
- (iii) **no unmeasured confounding**
- (iv) for PNDE and TNIE: **some parametric restrictions**

## Maternal BMI, childhood BMI and eating disorders

Results from g-computation and estimation-by-combination

Model	Estimand	Method			
		G-computation		Combination	
		Estimate	(s.e.)	Estimate	(s.e.)
<b>Model 1:</b> no $X$ - $M$ interaction					
	<i>TCE</i>	0.287	(0.049)	0.287	(0.052)
	<i>PNDE</i>	0.103	(0.047)	0.102	(0.050)
	<i>TNIE</i>	0.184	(0.019)	0.185	(0.021)
<b>Model 2:</b> $CDE(m)$ does not vary with $M(0)$					
	<i>TCE</i>	0.297	(0.047)	0.297	(0.049)
	<i>PNDE</i>	0.102	(0.051)	0.103	(0.051)
	<i>TNIE</i>	0.195	(0.026)	0.194	(0.028)

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Which of these models is best?

## Maternal BMI, childhood BMI and eating disorders

## Structural model for Bingeing/Overeating

Expl. var.	Model 1		Model 2		Model 3	
	No $X - M$ interaction		No $X - L$ nor $L^2$		No constraints	
	Estimate	(s.e.)	Estimate	(s.e.)	Estimate	(s.e.)
$X$	0.072	(0.048)	0.084	(0.049)	0.068	(0.050)
$M$	0.315	(0.019)	0.313	(0.021)	0.312	(0.021)
$M^2$	0.044	(0.012)	0.042	(0.012)	0.043	(0.012)
$L$	0.034	(0.022)	0.054	(0.020)	0.034	(0.022)
$L^2$	<b>0.032</b>	(0.012)	-	-	<b>0.032</b>	(0.012)
$XL$	<b>0.078</b>	(0.045)	-	-	<b>0.078</b>	(0.045)
$XM$	-	-	<b>0.017</b>	(0.045)	<b>0.014</b>	(0.045)
$C_1$	-0.011	(0.036)	-0.011	(0.036)	-0.011	(0.036)
$C_2$	0.207	(0.054)	0.209	(0.054)	0.207	(0.054)

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# References

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